Random Process

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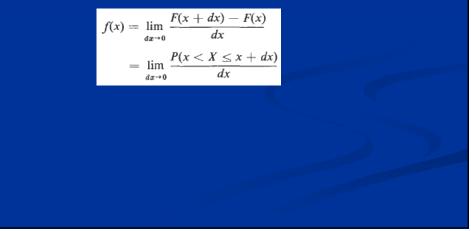
RANDOM VARIABLES

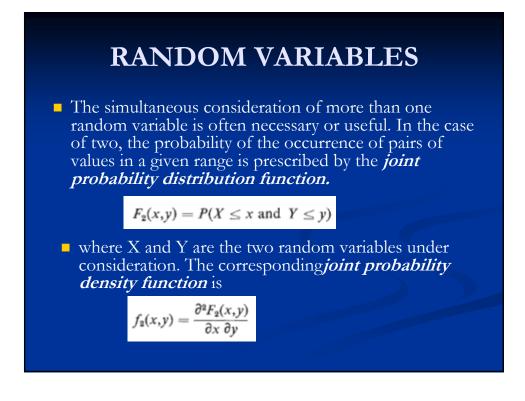
- A random variable X is in simplest terms a variable which takes on values at random; it may be thought of as a function of the outcomes of some random experiment.
- The manner of specifying the probability with which different values are taken by the random variable is by the probability distribution function F(x), which is defined by

$$F(x) = P(X \le x)$$
$$F(A) = \int_{-\infty}^{A} f(x) dx$$

RANDOM VARIABLES

From the definition, the interpretation of f (x) as the density of probability of the event that X takes a value in the vicinity of x is clear.





RANDOM VARIABLESFor the distribution of X,

$$F(x) = F_2(x, \infty)$$
$$f(x) = \int_{-\infty}^{\infty} f_2(x, y) \, dy$$

RANDOM VARIABLES

If X and Y are independent, the event X <= x is independent of the event Y <= y; thus the probability for the joint occurrence of these events is the product of the probabilities for the individual events.

$$F_2(x,y) = P(X \le x \text{ and } Y \le y)$$

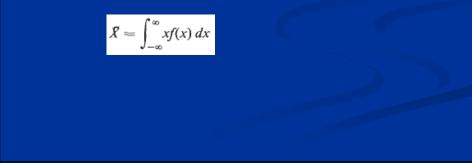
= $P(X \le x)P(Y \le y)$
= $F_X(x)F_Y(y)$

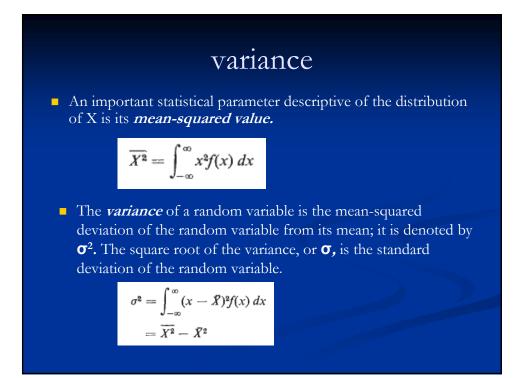
The joint probability density function is

$$f_2(x,y) = f_X(x)f_Y(y)$$

Expectations

- The *expectation* of a random variable is the sum of all values the random variable may take, each weighted by the probability with which the value is taken.
- This is also called the *mean value* of X, or the mean of the distribution of X.
- The expectation of X, which we denote by X is



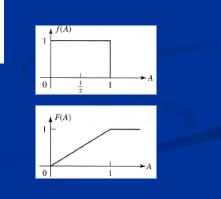


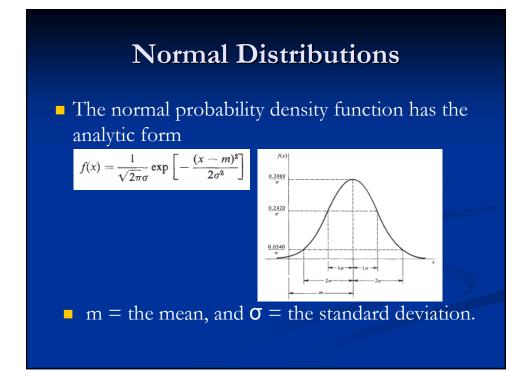


The uniform distribution is characterized by a uniform (constant) probability density over ome finite interval.



Probability density function f (A) and the probability distribution function F(A) of a uniformly distributed random variable A





Random Processes

- Gaussian processes play an important role in communication systems, such as the thermal noise in electronic devices, can be closely modeled by a Gaussian process.
- Definition: A random process X(t) is a Gaussian process if for all n and all (t1, t2, ..., tn), the random variables $\{X(t_1)\}_{i=1}^n$ have a jointly Gaussian density function, which may be expressed as

$$f(\mathbf{x}) = \frac{1}{(2\pi)^{n/2} [\det(\mathbf{C})]^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \mathbf{m})^t \mathbf{C}^{-1}(\mathbf{x} - \mathbf{m})\right]$$

- Where the vector x = (x1, x2, ..., xn)^t denotes the n random variables x_i ≡ X(t_i),
- m is the mean value vector, that is, m = E(X), and C is the n x n covariance matrix of the random variables (x1, x2, ..., xn) with elements

$$c_{ij} = E[(x_i - m_i)(x_j - m_j)]$$

From the above definition it is seen, in particular, that at any time instant /s the random variable X(t0) is Gaussian, and at any two points tl, t2 the random variables (X(t1), X(t2)) are distributed according to a two-dimensional Gaussian random variable.

- Property 1: For Gaussian processes, knowledge of the mean m and covariance C provides a complete statistical description of the process.
 - Another very important property of a Gaussian process is concerned with its characteristics when passed through a linear time-invariant system.
- Property 2: If the Gaussian process X(t) is passed through a linear time-invariant (LTI) system, the output of the system is also a Gaussian process. The effect of the system on X (t) is simply reflected by a change in the mean value and the covariance of X (t).

Markov Process

Definition: A Markov process X(t) is a random process whose past has no influence on the future if its present is specified; that is, if t_n > t_{n-1}, then

 $P[X(t_n) \le x_n \mid X(t), \quad t \le t_{n-1}] = P[X(t_n) \le x_n \mid X(t_{n-1})]$

 Definition: A Gauss-Markov process X(r) is a Markov process whose probability density function is Gaussian. Example, where w_n, is a sequence of zero-mean i.i.d. (white) random variables and p is a parameter that determines the degree of correlation between X_n and X_{n-1};

$$X_n = \rho X_{n-1} + w_n$$

$$E(X_n X_{n-1}) = \rho E(X_{n-1}^2) = \rho \sigma_{n-1}^2$$

If the sequence w_n is Gaussian, then the resulting process X(t) is a Gauss-Markov process.

Auto-korelasi

 Korelasi x(t) dengan dirinya sendiri disebut autokorelasi

$$R_{x}(t) = x(t) \oplus x(t) = \int_{0}^{\infty} x(\tau)x(t+\tau)d\tau$$

- Definition: A random process X (t) is called a white process if it has a flat power spectrum that is, if S_x (f) is a constant for all f.
- if $S_x(f) = C$ for all f, then

$$\int_{-\infty}^{\infty} \mathcal{S}_x(f) \, df = \int_{-\infty}^{\infty} C \, df = \infty$$

Power Spectrum of Random Processes

A stationary random process X(t) is characteized in the frequency domain by its power spectrum S_x(f), which is the Fourier transform of the autocorrelation function R_x(T) of the random process; that is,

$$S_x(f) = \int_{-\infty}^{\infty} R_x(\tau) e^{-j2\pi f\tau} dt$$
$$R_x(\tau) = \int_{-\infty}^{\infty} S_x(f) e^{j2\pi f\tau} df$$

